

A Proof Search Specification of the π -calculus

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Motivations

- To use logic, more precisely, *proof theory*, as a *framework* for specifying and reasoning about operational semantics.
- We focus on the presentation of operational semantics as *deductive systems*, e.g., structural operational semantics, and on computation as proof search.
- Reasoning about *mobility* of *names*. The kind of mobility we are considering: link mobility (as in π -calculus), which are basically the changing in scoping of names. Its operational aspects can (hopefully) be understood in the quantification theory of logic.

The λ -tree syntax encoding of operational semantics

- The usual presentations of SOS for name-passing calculi are not “syntax-directed” enough. Various side conditions on names and scoping of names need to be carefully stated along with the inference rules.
- We adopt an abstract syntax, called λ -tree syntax. λ -tree syntax is a logic programming approach to *higher-order abstract syntax*.
- It is based on simply typed λ -calculus: abstractions in process calculi are represented using λ -abstraction, and process constructors are represented as constants with appropriate types. Capture-avoiding substitution is modelled by β -reduction.

An example of λ -tree syntax encoding

An inference rule for (late) transition system of π -calculus:

$$\frac{P \xrightarrow{\alpha} P' \quad x \notin \mathfrak{n}(\alpha)}{(x)P \xrightarrow{\alpha} (x)P'}$$

$$\frac{\forall x (Px \xrightarrow{A} P'x)}{\nu(\lambda x.Px) \xrightarrow{A} \nu(\lambda x.P'x)}$$

P, P' and A are *scheme variables*, subject to *capture avoiding* substitutions. The constants ν is of type $(n \rightarrow p) \rightarrow p$ where the types n and p denote names and processes.

Since substitution is capture-avoiding, the scheme variable A cannot be instantiated with term containing free occurrences of x .

Sequents and generic judgments

We use Gentzen's *sequent calculus* for presenting our logic. A sequent is an expression of the form

$$\Sigma; B_1, \dots, B_n \vdash B_0$$

where B_0, \dots, B_n are formulas and Σ is the *signature* of the sequent, containing declarations of the free variables in each B_i (also called *eigenvariables*).

To capture properly the notion of name restriction in process calculi, we enrich sequents with locally bound variables within the formulas:

$$\Sigma; \sigma_1 \triangleright B_1, \dots, \sigma_n \triangleright B_n \vdash \sigma_0 \triangleright B_0$$

where σ_i is a list of variables locally scoped over B_i .

Variables in σ_i are binding occurrences, so the usual α -equivalence applies.

Overview of $FO\lambda^{\Delta\nabla}$: propositional fragment

$$\frac{}{\Sigma; \sigma \triangleright A, \Gamma \vdash \sigma \triangleright A} \textit{init}$$

$$\frac{\Sigma; \Delta \vdash \mathcal{B} \quad \Sigma; \mathcal{B}, \Gamma \vdash \mathcal{C}}{\Sigma; \Delta, \Gamma \vdash \mathcal{C}} \textit{cut}$$

$$\frac{}{\Sigma; \sigma \triangleright \perp, \Gamma \vdash \mathcal{B}} \perp \mathcal{L}$$

$$\frac{}{\Sigma; \Gamma \vdash \sigma \triangleright \top} \top \mathcal{R}$$

$$\frac{\Sigma; \mathcal{B}, \mathcal{B}, \Gamma \vdash \mathcal{C}}{\Sigma; \mathcal{B}, \Gamma \vdash \mathcal{C}} \textit{c}\mathcal{L}$$

$$\frac{\Sigma; \Gamma \vdash \mathcal{C}}{\Sigma; \mathcal{B}, \Gamma \vdash \mathcal{C}} \textit{w}\mathcal{L}$$

$$\frac{\Sigma; \sigma \triangleright B_i, \Gamma \vdash \mathcal{D}}{\Sigma; \sigma \triangleright B_1 \wedge B_2, \Gamma \vdash \mathcal{D}} \wedge \mathcal{L}$$

$$\frac{\Sigma; \Gamma \vdash \sigma \triangleright B_1 \quad \Sigma; \Gamma \vdash \sigma \triangleright B_2}{\Sigma; \Gamma \vdash \sigma \triangleright B_1 \wedge B_2} \wedge \mathcal{R}$$

$$\frac{\Sigma; \sigma \triangleright B_1, \Gamma \vdash \mathcal{D} \quad \Sigma; \sigma \triangleright B_2, \Gamma \vdash \mathcal{D}}{\Sigma; \sigma \triangleright B_1 \vee B_2, \Gamma \vdash \mathcal{D}} \vee \mathcal{L}$$

$$\frac{\Sigma; \Gamma \vdash \sigma \triangleright B_i}{\Sigma; \Gamma \vdash \sigma \triangleright B_1 \vee B_2} \vee \mathcal{R}$$

$$\frac{\Sigma; \Gamma \vdash \sigma \triangleright B \quad \Sigma; \sigma \triangleright C, \Gamma \vdash \mathcal{D}}{\Sigma; \sigma \triangleright B \supset C, \Gamma \vdash \mathcal{D}} \supset \mathcal{L}$$

$$\frac{\Sigma; \sigma \triangleright B, \Gamma \vdash \sigma \triangleright C}{\Sigma; \Gamma \vdash \sigma \triangleright B \supset C} \supset \mathcal{R}$$

Overview of $FO\lambda^{\Delta\nabla}$: quantifiers

$$\frac{\Sigma; (\sigma, y : \tau) \triangleright B[y/x], \Gamma \vdash \mathcal{C}}{\Sigma; \sigma \triangleright \nabla_{\tau} x. B, \Gamma \vdash \mathcal{C}} \nabla \mathcal{L}$$

$$\frac{\Sigma; \Gamma \vdash (\sigma, y : \tau) \triangleright C[y/x]}{\Sigma; \Gamma \vdash \sigma \triangleright \nabla_{\tau} x. C} \nabla \mathcal{R}$$

$$\frac{\Sigma, \sigma \vdash t : \gamma \quad \Sigma; \sigma \triangleright B[t/x], \Gamma \vdash \mathcal{C}}{\Sigma; \sigma \triangleright \forall_{\gamma} x. B, \Gamma \vdash \mathcal{C}} \forall \mathcal{L}$$

$$\frac{\Sigma, h; \Gamma \vdash \sigma \triangleright B[(h \sigma)/x]}{\Sigma; \Gamma \vdash \sigma \triangleright \forall x. B} \forall \mathcal{R}$$

$$\frac{\Sigma, h; \sigma \triangleright B[(h \sigma)/x], \Gamma \vdash \mathcal{C}}{\Sigma; \sigma \triangleright \exists x. B, \Gamma \vdash \mathcal{C}} \exists \mathcal{L}$$

$$\frac{\Sigma, \sigma \vdash t : \gamma \quad \Sigma; \Gamma \vdash \sigma \triangleright B[t/x]}{\Sigma; \Gamma \vdash \sigma \triangleright \exists_{\gamma} x. B} \exists \mathcal{R}$$

Overview of $FO\lambda^{\Delta\nabla}$: raising of types

Dependency between eigenvariables and local variables is encoded using the technique of \forall -lifting [Paulson] or *raising* [Miller92] of the types of the eigenvariables. Example:

$$\frac{\frac{\{x_\alpha, h_{\tau \rightarrow \gamma \rightarrow \beta}\}; \Gamma \vdash (a_\tau, b_\gamma) \triangleright B \quad (h a b) b}{\{x_\alpha\}; \Gamma \vdash (a_\tau, b_\gamma) \triangleright \forall_\beta y. B \quad y b} \forall \mathcal{L}}{\{x_\alpha\}; \Gamma \vdash (a_\tau) \triangleright \nabla_\gamma z. \forall_\beta y. B \quad y z} \nabla \mathcal{R}$$

Overview of $FO\lambda^{\Delta\nabla}$: a notion of definitions

We extend the logic further by allowing a non-logical constants (predicate) to be introduced. To each predicate, we associate some *definition clauses*. We write

$$\forall \bar{x}. p \bar{x} \triangleq B \bar{x}$$

to denote a definition clause for predicate p . This notion of definition has been previously studied by Schroeder-Heister, Girard, Miller and McDowell.

Definitions and Equality

The usual form of definitions allows matching on the head of definition, e.g.,

$$\begin{aligned} \mathit{nat} \ z &\triangleq \top. \\ \mathit{nat} \ (sX) &\triangleq \mathit{nat} \ X. \end{aligned}$$

In our setting, pattern matching is encoded explicitly as equations, e.g.,

$$\mathit{nat} \ X \triangleq (X = z) \vee \exists Y. (X = (sY) \wedge \mathit{nat} \ Y).$$

These two presentations are equivalent. We use the former in presenting examples and the latter for meta-theoretic discussions.

Introduction rules for definitions and equality

$$\frac{\Gamma \vdash \sigma \triangleright B \bar{t}}{\Gamma \vdash \sigma \triangleright p \bar{t}} \text{ def}\mathcal{R}$$

$$\frac{\Gamma, \sigma \triangleright B \bar{t} \vdash \mathcal{C}}{\Gamma, \sigma \triangleright p \bar{t} \vdash \mathcal{C}} \text{ def}\mathcal{R}$$

where $\forall \bar{x}. [p \bar{x} \stackrel{\Delta}{=} B \bar{x}]$

$$\frac{\{\Gamma \theta \vdash C \theta \mid \theta \in CSU(\lambda \bar{x}.s, \lambda \bar{x}.t)\}}{\bar{x} \triangleright s = t, \Gamma \vdash C} \text{ eq}\mathcal{L}$$

$$\overline{\Gamma \vdash \sigma \triangleright t = t}$$

Specification of π -calculus

We consider the finite fragment of π -calculus (no replication or recursion):

$$P ::= 0 \mid \tau.P \mid x(y).P \mid \bar{x}y.P \mid (P \mid P) \mid (P + P) \mid (x)P \mid [x = y]P$$

To encode the process expressions in λ -tree syntax, we introduce the types n (names), p (processes), and the following constants

$$\begin{aligned} 0 &: p, & \tau &: p \rightarrow p, & out &: n \rightarrow n \rightarrow p \rightarrow p, & in &: n \rightarrow (n \rightarrow p) \rightarrow p, \\ + &: p \rightarrow p \rightarrow p, & | &: p \rightarrow p \rightarrow p, & match &: n \rightarrow n \rightarrow p \rightarrow p, & \nu &: (n \rightarrow p) \rightarrow p. \end{aligned}$$

Translation to λ -tree syntax: process expressions

$$\begin{aligned} \llbracket 0 \rrbracket &= 0, \\ \llbracket [x = y]P \rrbracket &= \mathit{match} \ x \ y \ \llbracket P \rrbracket, \\ \llbracket [\bar{x}y].P \rrbracket &= \mathit{out} \ x \ y \ \llbracket P \rrbracket, \\ \llbracket [x(y).P] \rrbracket &= \mathit{in} \ x \ \lambda y. \llbracket P \rrbracket, \\ \llbracket P + Q \rrbracket &= \llbracket P \rrbracket + \llbracket Q \rrbracket, \\ \llbracket P | Q \rrbracket &= \llbracket P \rrbracket | \llbracket Q \rrbracket, \\ \llbracket [\tau].P \rrbracket &= \tau \ \llbracket P \rrbracket, \\ \llbracket [(x)P] \rrbracket &= \nu \lambda x. \llbracket P \rrbracket. \end{aligned}$$

Translation to λ -tree syntax: one-step transitions

We introduce the type a to denote *actions*. One-step transition judgments are encoded as follows.

$$\begin{array}{l} \llbracket P \xrightarrow{\bar{x}y} Q \rrbracket = \llbracket P \rrbracket \xrightarrow{\uparrow xy} \llbracket Q \rrbracket \quad \llbracket P \xrightarrow{\tau} Q \rrbracket = \llbracket P \rrbracket \xrightarrow{\tau} \llbracket Q \rrbracket \\ \llbracket P \xrightarrow{x(y)} Q \rrbracket = \llbracket P \rrbracket \xrightarrow{\downarrow x} \lambda y. \llbracket Q \rrbracket \quad \llbracket P \xrightarrow{\bar{x}(y)} Q \rrbracket = \llbracket P \rrbracket \xrightarrow{\uparrow x} \lambda y. \llbracket Q \rrbracket \end{array}$$

where $\downarrow: n \rightarrow n \rightarrow a$ encodes *input action* and $\uparrow: n \rightarrow n \rightarrow a$ encodes *output action*. Transitions involving *bound actions* are encoded as

$$\cdot \xrightarrow{\cdot} \cdot : p \rightarrow a \rightarrow (n \rightarrow p)$$

Specification of (late) transition system of π -calculus

Some sample clauses:

$$\frac{P \xrightarrow{A} Q}{(x)P \xrightarrow{\alpha} (x)Q} \quad x \notin \text{fn}(\alpha)$$

$$\nu x.Mx \xrightarrow{A} \nu x.Nx \triangleq \nabla x(Mx \xrightarrow{A} Nx).$$

$$\nu x.Mx \xrightarrow{A} \lambda y \nu x.Nxy \triangleq \nabla x(Mx \xrightarrow{A} Nx).$$

$$\frac{P \xrightarrow{\alpha} Q}{[x = x]P \xrightarrow{\alpha} Q}$$

$$\text{match } x \ x \ P \xrightarrow{A} Q \triangleq P \xrightarrow{A} Q.$$

$$\text{match } x \ x \ P \xrightarrow{A} M \triangleq P \xrightarrow{A} M.$$

$$\frac{P \xrightarrow{\bar{x}w} P'}{(y)P \xrightarrow{\bar{x}(w)} P'[w/y]} \quad \begin{array}{l} y \neq x, \\ w \notin \text{fn}((y)P') \end{array}$$

$$\nu y.My \xrightarrow{\uparrow X} M' \triangleq \nabla y(My \xrightarrow{\uparrow Xy} M'y).$$

Example: one-step transition

Consider the process $(y)[x = y]\bar{x}z.0$. It cannot make any transition, since y has to be “fresh”.

$$\begin{array}{c}
 \frac{}{\{x, z, Q, \alpha\}; y \triangleright ([x = y](\bar{x}z.0) \xrightarrow{\alpha} Q) \vdash \perp} \text{def}\mathcal{L} \\
 \frac{}{\{x, z, Q, \alpha\}; . \triangleright \nabla y.([x = y](\bar{x}z.0) \xrightarrow{\alpha} Q) \vdash \perp} \nabla\mathcal{L} \\
 \frac{}{\{x, z, Q, \alpha\}; . \triangleright ((y)[x = y](\bar{x}z.0) \xrightarrow{\alpha} Q) \vdash \perp} \text{def}\mathcal{L} \\
 \frac{}{\{x, z, Q, \alpha\}; \vdash . \triangleright ((y)[x = y](\bar{x}z.0) \xrightarrow{\alpha} Q) \supset \perp} \supset \mathcal{R}
 \end{array}$$

The success of $\text{def}\mathcal{L}$ depends on the failure of unification problem

$$\lambda y.x = \lambda y.y.$$

Specification of late bisimulation

$$\begin{aligned}
\text{lbisim } P \ Q \triangleq & \forall A \forall P' [(P \xrightarrow{A} P') \supset \exists Q'. (Q \xrightarrow{A} Q') \wedge \text{lbisim } P' \ Q'] \wedge \\
& \forall A \forall Q' [(Q \xrightarrow{A} Q') \supset \exists P'. (P \xrightarrow{A} P') \wedge \text{lbisim } Q' \ P'] \wedge \\
& \forall X \forall P' [(P \xrightarrow{\downarrow X} P') \supset \exists Q'. (Q \xrightarrow{\downarrow X} Q') \wedge \forall w. \text{lbisim } (P'w) \ (Q'w)] \wedge \\
& \forall X \forall Q' [(Q \xrightarrow{\downarrow X} Q') \supset \exists P'. (P \xrightarrow{\downarrow X} P') \wedge \forall w. \text{lbisim } (Q'w) \ (P'w)] \wedge \\
& \forall X \forall P' [(P \xrightarrow{\uparrow X} P') \supset \exists Q'. (Q \xrightarrow{\uparrow X} Q') \wedge \nabla w. \text{lbisim } (P'w) \ (Q'w)] \wedge \\
& \forall X \forall Q' [(Q \xrightarrow{\uparrow X} Q') \supset \exists P'. (P \xrightarrow{\uparrow X} P') \wedge \nabla w. \text{lbisim } (Q'w) \ (P'w)]
\end{aligned}$$

The need for case split on names

The previous specification is *not* complete. Consider $P = x(u).(\tau.\tau + \tau)$ and $Q = x(u).(\tau.\tau + \tau + \tau.[u = y]\tau)$ and checking $P \sim Q$.

$$Q \xrightarrow{x(u)} \tau.\tau + \tau + \tau.[u = y]\tau \xrightarrow{\tau} [u = y]\tau$$

$$P \xrightarrow{x(u)} \tau.\tau + \tau \longrightarrow ?$$

Here the names u and y are encoded as eigenvariables in logic. The possible matching moves of P :

- (1) $\tau.\tau + \tau \xrightarrow{\tau} \tau$ if u is equal to y
- (2) $\tau.\tau + \tau \xrightarrow{\tau} 0.$, if u is not equal to y

Since name is not inductively defined, this case split cannot be captured intuitionistically.

Adequacy of Ibisim

To get a complete encoding of late bisimulation we need to add explicitly excluded middle on names, i.e., the set

$$\mathcal{E} = \left\{ \begin{array}{l} \forall x \forall y (x = y \vee x \neq y), \\ \nabla n_1 \forall x \forall y (x = y \vee x \neq y), \\ \nabla n_1 \nabla n_2 \forall x \forall y (x = y \vee x \neq y), \\ \vdots \end{array} \right\}$$

Theorem 1. *Let P and Q be two processes and let \bar{n} be the free names in P and Q . Then $P \sim_l Q$ if and only if the sequent*

$$.; \mathcal{X} \vdash \nabla \bar{n}. \text{Ibisim } P \ Q$$

is provable for some $\mathcal{X} \subseteq_f \mathcal{E}$.

Open bisimulation

What does $\text{Ibisim } P \ Q$ correspond to (without the excluded middle assumption)?

It turns out that if we drop the excluded middle axiom and \forall -quantify all the free names in P and Q we get a sound and complete encoding of *open bisimulation* [Sangiorgi].

Names in open bisimulation are instantiated lazily, and this bisimulation is closed under arbitrary substitution of free names.

Automation of proof search

- Proof search strategy for open bisimulation: apply left-introduction rules if applicable, otherwise apply right introduction rules. This proof strategy is *complete*.
- Proof search strategy for late bisimulation: need to know when to use the excluded middle on names. A complete proof strategy would be to do case split early, e.g., doing $n + 1$ case split for processes with n distinct free names.

Implementation

- Implementation is rather straightforward: it is based on known old technology, e.g., HOAS based on Church's simply typed λ -calculus, higher-order pattern unification, and other related implementation techniques for logic programming.
- We currently have a working prototype implementation for (automated) checking of open bisimulation. Available from the web: <http://www.loria.fr/~tiu>

Related work

- Formalization of π -calculus has been done in different frameworks, e.g., in Coq [Hirschhoff TPHOL'97, Despeyroux IFIP-TCS'00, Honsell et. al. TCS'01], in nominal logic [Gabbay'03].
- In those works, formalizing freshness of names, scoping, substitution, etc., is considerable work. In our framework, the same work has to be done, but it is done as a part of the description of the logic. Formalization of open bisimulation, as far as we know, has not been done prior to our work.
- Formalization of π -calculus with replication has been done in [Tiu'04].

Future work

- Relation with *symbolic bisimulation*. Find correspondence between decision procedure in, e.g., [Hennessy and Lin, TCS'95] and [Boreale and Nicola, IC. 96], to proof search.
- Formalizing other systems. Current work in progress: spi-calculus and framed bisimulation, modal logics for π -calculus.
- Proof procedures for bisimulation checking for non-terminating processes, e.g., via *circular proofs*, tabled deduction, domain specialized proof procedures, etc.